

Appl. No. 10/605,778
Response dated 10/4/2005
Reply to Office Action of 4/4/2005

AMENDMENTS TO CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims

1. (currently amended) A system comprising:
a platform coupled with two freely rotating sheaves each coupled to opposing sides of said platform wherein no sheave coupled with said platform is coupled with a brakesheaves that do not comprise brakes;
a YZ movement rope configured to move said platform;
a Z movement device configured to move said YZ movement rope;
a Y movement motor coupled with said YZ movement rope;
a Z movement motor coupled with said Z movement device; and,
a computer coupled with said Y movement motor and said Z movement motor and configured to control said YZ movement rope to move said platform in a Y axis and a Z axis via said YZ movement rope.
- 2-12 (canceled)
13. (original) The system of claim 1 further comprising at least two support structures.
14. (currently amended) A method comprising:
coupling a YZ movement rope with two freely rotating sheaves each coupled to opposing sides of a platform wherein no sheave coupled with said platform is coupled with a brakete-a platform via sheaves that do not comprise brakes;
coupling a Z movement device to said YZ movement rope;
coupling said YZ movement rope to a Y movement motor;
coupling said Z movement device to a Z movement motor;
coupling a computer with said Y movement motor and said Z movement motor; and,

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controlling said YZ movement rope in a Y axis and a Z axis with said computer by rotating said Y movement motor and rotating said Z movement motor in order to move said platform via said YZ movement rope.

15. (canceled)

16. (canceled)

17. (currently amended) A system comprising:

means for coupling a YZ movement rope ~~to a platform with two freely rotating sheaves each coupled to opposing sides of a platform wherein no sheave coupled with said platform is coupled with a brake via sheaves that do not comprise brakes;~~

means for coupling a Z movement device to said YZ movement rope;

means for coupling said YZ movement rope to a Y movement motor;

means for coupling said Z movement device to a Z movement motor;

means for coupling a computer with said Y movement motor and said Z movement motor; and,

means for controlling said YZ movement rope in a Y axis and a Z axis with said computer coupled to rotate said Y movement motor and rotate said Z movement motor in order to move said platform via said YZ movement rope.

18-20 (canceled)